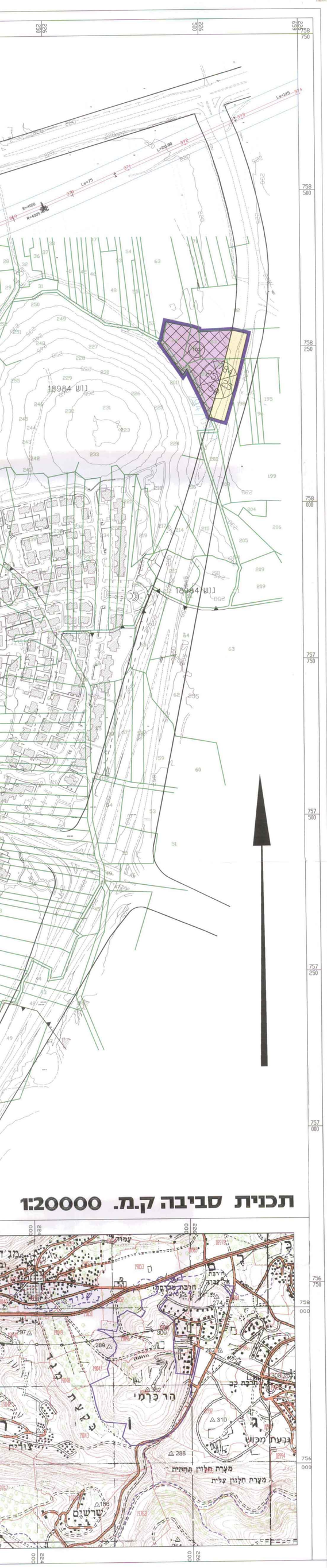

תכנית סביבה ק.מ. 1:20000

מצב מוצא ק.מ. 1:2500